

# Computational Reflection: Automatically Proving Difficult Things

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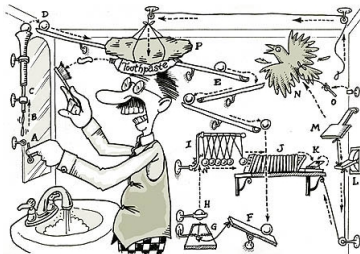
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# Computational Reflection

Suppose we are proving the correctness of some system,



<http://hhe.wikispaces.com/Rube+Goldberg+Machines>

Part way through the proof, we must show:

$\vdash$   
 $\{1\} \text{ EXISTS } (x:\text{real}): 3x^2 - 5x + 2 = 0$

# Computational Reflection

A little while later, we have to prove:

$\vdash$   
 $\{1\} \text{ EXISTS } (x:\text{real}): 2x^2 - 3x + 1 = 0$

And later,

$\vdash$   
 $\{1\} \text{ EXISTS } (x:\text{real}): 12x^2 - 10x + 2 = 0$

In each case, we prove this by instantiating formula 1 with a real number  $x$  that makes the equality true.

But we don't need to know the exact solutions to these equations to know that they are true.

# Computational Reflection

By the quadratic formula, the equation

$$ax^2 + bx + c = 0$$

has a solution if and only if  $b^2 - 4ac \geq 0$ .

In PVS, we can define a function on  $a$ ,  $b$ , and  $c$  that returns a boolean:

```
D(a,b,c:real): bool = b^2 - 4*a*c >= 0
```

We can then prove the following lemma in PVS

```
quadratic_solvable : LEMMA
  FORALL (a,b,c:real):
    (EXISTS (x:real): a x^2 -b*x+c = 0)
      IFF
      D(a,b,c)
```

## Computational Reflection

Now we can solve all of those lemmas by just evaluating D.

The next time we have to prove something like

```
|-  
{1} EXISTS (x:real): 2 x^2 -3*x+1 = 0
```

we can just type

```
(lemma ‘quadratic_solvable’)  
(inst?)  
(assert)  
(hide  
(-1 -2))
```

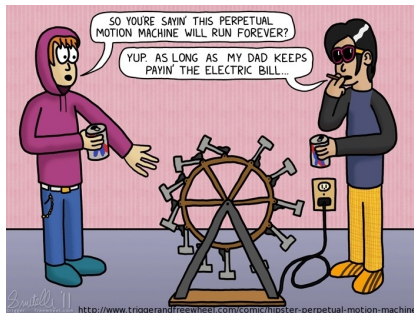
which turns the sequent into

```
|-  
{1} D(2,-3,1)
```

This proves with

```
(grind)
```

# What if we tried to prove something that is false???



Part way through the proof, we must show:

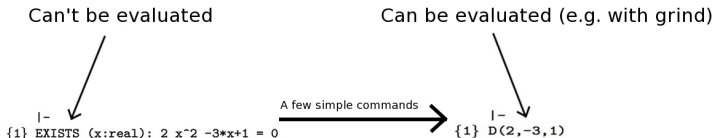
$\vdash$   
 $\{1\} \text{ EXISTS } (x:\text{real}): 10 x^2 - 2x + 1 = 0$

This **FAILS**:

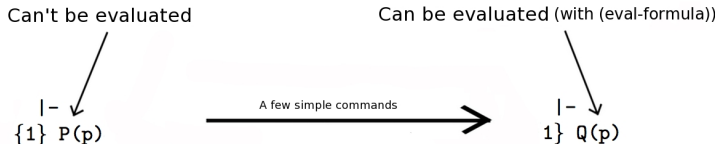
```
(lemma 'quadratic_solvable')  
(inst?)  
(assert)  
(hide (-1 -2))  
(grind)
```

# Computational Reflection

Proving that a quadratic has a root:

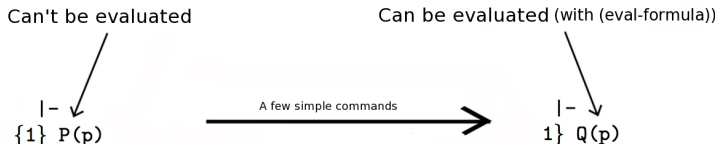


Computational reflection is similar:



# Computational Reflection

Computational reflection:



- ▶ We have some type  $T$  (e.g. quadratics)
- ▶ We often want to prove a property of  $P(p)$  for some  $p \in T$
- ▶ The property  $P(p)$  can not be evaluated
- ▶  $Q(p)$  is equivalent to  $P(p)$
- ▶  $Q(p)$  can be evaluated!



# Computational Reflection

Computational reflection:

- ▶  $Q(p)$  is equivalent to  $P(p)$  and can be evaluated

Sometimes (grind) can be inefficient.

Let's prove

$$\begin{array}{c} \vdash \\ \{1\} \text{ EXISTS } (x:\text{real}): 2^{400} * x^2 + 2^{600}x + 2^{100} = 0 \end{array}$$

The same proof works as before. The sequent is reduced to proving

$$\begin{array}{c} \vdash \\ \{1\} D(2^{400}, 2^{600}, 2^{100}) \end{array}$$

This proves with (grind)

# Computational Reflection

$\vdash$   
 $\{1\} \ D(2^{400}, 2^{600}, 2^{100})$

This proves with (grind)...

but it takes more than a minute.

- ▶ What if we have to prove many results like this?
- ▶ What if the function  $D$  were significantly more complicated?

(grind) is not very efficient for evaluating complicated expressions

PVS is not really a programming language. We'd like to evaluate this expression as fast as we could in a programming language.

# Computational Reflection

We can evaluate

$\vdash$   
 $\{1\} \text{ D}(2^{400}, 2^{600}, 2^{100})$

using

`(eval-formula)`

THIS is computational reflection

# Computational Reflection

- ▶ The property  $Q(p)$  is equivalent to  $P(p)$  and can be evaluated

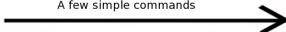
Can't be evaluated

$\vdash_{\{1\}} P(p)$

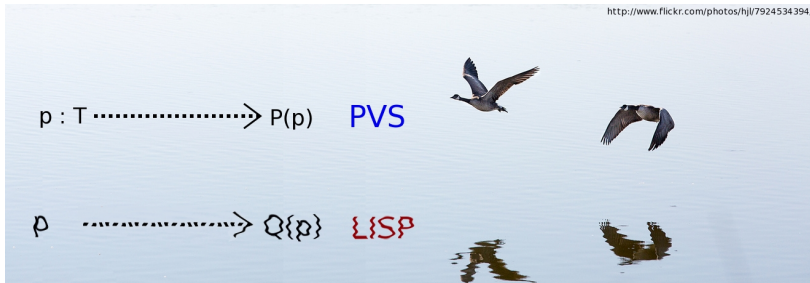
Can be evaluated (with (eval-formula))

$\vdash_1 Q(p)$

A few simple commands



# Why is it Called Reflection?



- ▶ PVS is built on top of LISP
- ▶ The problem is reflected down to LISP
- ▶ ... and computed there

## Ground Terms

To compute  $Q(p)$  in LISP using (eval-formula), all of the atoms involved must be ground terms

That is, it has to be something that the programming language can compute

For instance, if  $a \in \mathbb{R}$ , it can't compute

IF  $a^2 \geq 0$  THEN 1 ELSE 0 ENDIF

which is equal to 1, because  $a^2$  is not ground.

However, it can compute

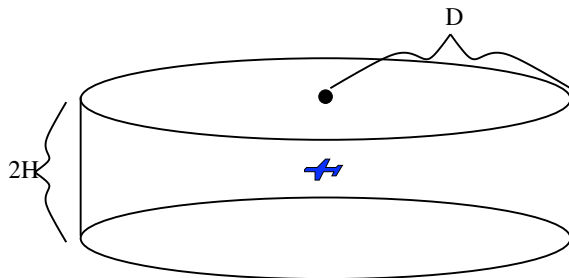
IF  $2^2 \geq 0$  THEN 1 ELSE 0 ENDIF

# Example: Conflict Detection

## Conflicts

- ▶ Minimum Horizontal Distance  $D$
- ▶ Minimum Vertical Distance  $H$

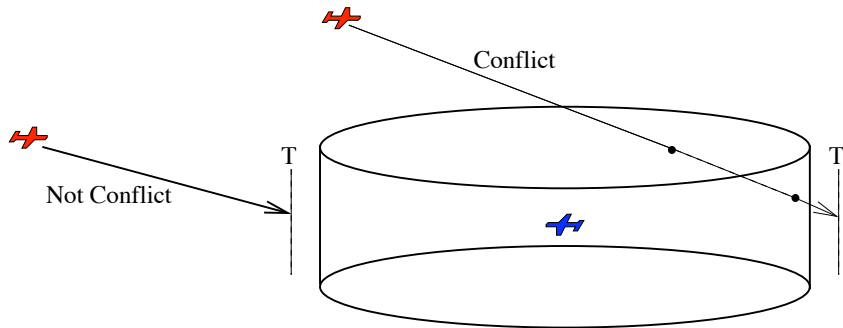
*The Protected Zone: A Cylinder*



## Example: Conflict Detection

The Problem: Detect Conflicts Within a Lookahead Time  $T$

Conflict: *Exists a time  $t \in [0, T]$  such that the red plane is inside the cylinder at time  $t$ .*





## Example: Conflict Detection

Aircraft	Position	Velocity
ownship	$\mathbf{s}_o$	$\mathbf{v}_o$
intruder	$\mathbf{s}_i$	$\mathbf{v}_i$
relative	$\mathbf{s} = \mathbf{s}_o - \mathbf{s}_i$	$\mathbf{v} = \mathbf{v}_o - \mathbf{v}_i$

$$\text{conflict?}(D, H, \mathbf{s}, \mathbf{v}) \equiv \exists t \geq 0 : \|\mathbf{s} + t\mathbf{v}\| < D \text{ and } |s_z + tv_z| < H$$

This is **not computable**

## Example: Conflict Detection

Project: Take 10K examples of near-conflicts and prove that none of them are actual conflicts.

Problem: Analyzing them individually would be very slow since  $\text{conflict?}(D, H, \mathbf{s}, \mathbf{v})$  can't be evaluated.

Solution: Replace  $\text{conflict?}(D, H, \mathbf{s}, \mathbf{v})$  with something equivalent that can be evaluated (computational reflection)

# Example: Conflict Detection

cd3d is an algorithm that computes whether  $\text{conflict?}(D, H, s, v)$  holds.

```
cd3d?(s,v) : bool =
  IF v`z = 0 AND abs(s`z) < H
  THEN sqv(vect2(s) + B * vect2(v)) < sq(D) OR
    IF sqv(vect2(s)) = sq(D) AND B = 0 THEN vect2(s) * vect2(v)
    ELSE sq(min(max(B * sqv(vect2(v)), -(vect2(s) * vect2(v))),
      T * sqv(vect2(v))))
      + sqv(vect2(v)) * sqv(vect2(s)) + 2 * (min(max(B * sqv(vect2(v)), -(vect2(s) * vect2(v))),
      T * sqv(vect2(v))) * (vect2(s) * vect2(v))) - sq(D) * sqv(vect2(v))
    ENDIF < 0
  ELSEIF v`z /= 0 AND
    max(-H - sign(v`z) * s`z, B * abs(v`z)) <
    min(H - sign(v`z) * s`z, T * abs(v`z))
  THEN sqv(vect2(abs(v`z) * s) + max(-H - sign(v`z) * s`z, B * abs(v`z)) * vect2(v))
    < sq(D * abs(v`z))
  OR
  IF sqv(vect2(abs(v`z) * s)) = sq(D * abs(v`z)) AND
    max(-H - sign(v`z) * s`z, B * abs(v`z)) = 0
  THEN vect2(abs(v`z) * s) * vect2(v)
  ELSE sq(min(max(max(-H - sign(v`z) * s`z, B * abs(v`z)) * sqv(vect2(v)),
    -(vect2(abs(v`z) * s) * vect2(v))),
    min(H - sign(v`z) * s`z, T * abs(v`z)) * sqv(vect2(v)))
    + sqv(vect2(v)) * sqv(vect2(abs(v`z) * s)) + 2 *
    (min(max(max(-H - sign(v`z) * s`z, B * abs(v`z)) * sqv(vect2(v)),
    -(vect2(abs(v`z) * s) * vect2(v))),
    min(H - sign(v`z) * s`z, T * abs(v`z)) * sqv(vect2(v)))
    * (vect2(abs(v`z) * s) * vect2(v)))
    - sq(D * abs(v`z)) * sqv(vect2(v))
  ENDIF < 0
  ELSE FALSE
ENDIF
```

cd3d\_correct : LEMMA

FORALL (s,v:Vect3,D,H:posreal):

conflict?(D,H,s,v)

IFF

cd3d(D,H,s,v)

## Example: Conflict Detection

Given 10K lemmas of the form

```
not_conflict_8741: LEMMA
  D = 5 AND
  H = 1000 AND
  s = (21,-5,-100) AND
  v = (-551,-1,300)
  IMPLIES
  NOT conflict?(D,H,s,v)
```

... the proofs are all the same and do not involve the actual numbers.

*conflict?* is replaced by *cd3d*, which is then evaluated using (eval-formula).

## Example: Conflict Detection

```
{-1} conflict?(D,H,s,v)
{-2} D = 5
{-3} H = 1000
{-4} s = (21,-5,-100)
{-5} v = (-551,-1,300)
|-
```

```
(replaces -2)
(replaces -2)
(replaces -2)
(replaces -2)
(lemma "cd3d_correct")
(inst?)
(assert)
(hide -1)
```

```
{-1} cd3d(5,1000,(21,-5,-100),(-551,-1,300))
|-
```

```
(eval-formula)
```

# Making the Proofs Even Easier

All of the proofs are the same.

We can create a single command that will execute the entire proof.

Let's call it (noconflict).

This is called a strategy.

After defining it, every lemma of the form

```
not_conflict_8741: LEMMA
  D = 5 AND
  H = 1000 AND
  s = (21,-5,-100) AND
  v = (-551,-1,300)
  IMPLIES
  NOT conflict?(D,H,s,v)
```

can be proved by just typing

```
(noconflict)
```

# Strategies and Computational Reflection

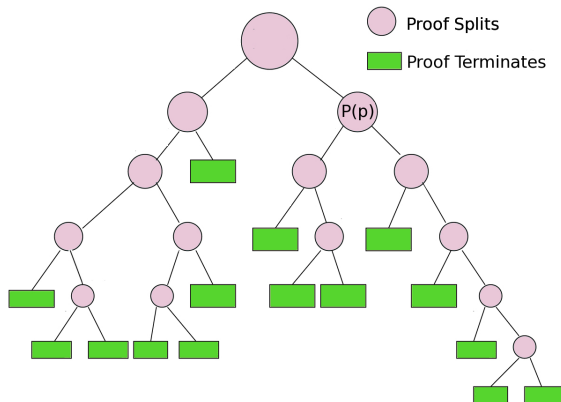
The command

```
(noconflict)
```

is called a strategy.

The combination of a strategy with computational reflection is very powerful for proving results with complicated proofs very quickly.

# Recursion and Computational Reflection



- ▶ A proof tree can be complicated
- ▶ A strategy can form the tree automatically in PVS



# Recursion and Computational Reflection

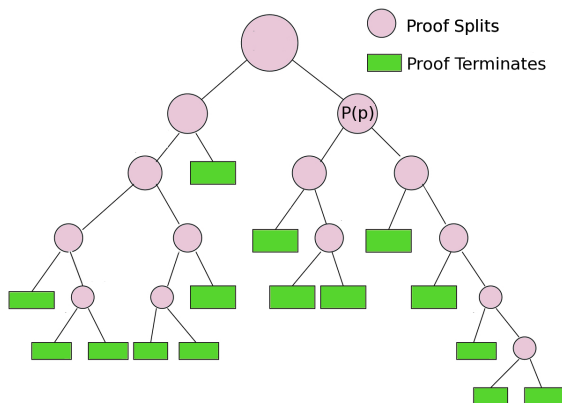
It isn't hard to decide when you need to split:



Yogi Berra: *"When you come to a fork in the road, take it!"*

- ▶ PVS can figure this out as well
- ▶ A strategy can tell PVS to split at each splitting node so that forming the tree is automatic
- ▶ It can also prove the result at each terminating node

# Recursion and Computational Reflection



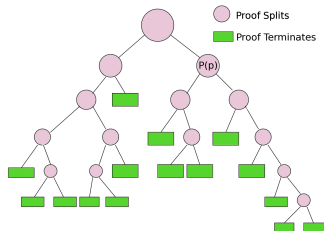
- ▶ The proof in PVS is as big as the tree
- ▶ All of this is done in PVS
- ▶ Even if we use reflection on the terminating nodes, forming a huge tree is slow in PVS

# When Computational Reflection is Really Powerful

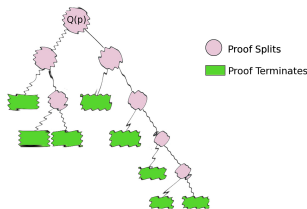
- ▶ Define the reflection function  $Q(p)$  as a recursive function that computes the whole tree
- ▶ ... and determines whether the result is true
- ▶ Then the proof in PVS is just reduced to evaluating  $Q(p)$  in PVS
- ▶ Which it does recursively in LISP by recreating the tree

## When Computational Reflection is Really Powerful

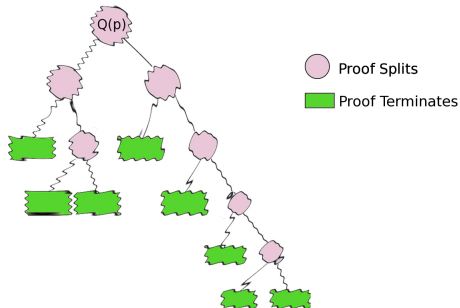
Instead of having PVS develop a proof that looks like



Define the recursive reflection function  $Q(p)$  in LISP whose execution looks like



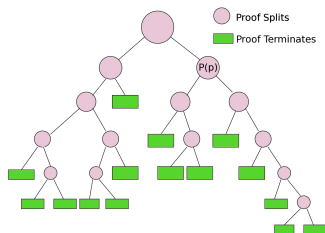
# When Computational Reflection is Really Powerful



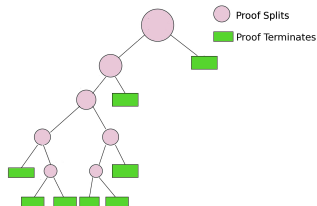
After proving  $P(p)$  in this way, the branch of the proof tree where  $P(p)$  was proved is now a single node

## When Computational Reflection is Really Powerful

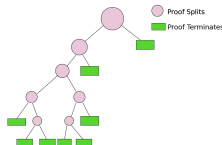
## The proof tree



becomes



# When Computational Reflection is Really Powerful



- ▶ Now the proof has the same length in PVS regardless of the size of the sub-tree where  $P(p)$  is proved
- ▶ But this is not always possible
- ▶ Every node in the recursion of  $Q(p)$  must be composed of only ground terms
- ▶ So no variables, existential quantifiers, infinite universal quantifiers, or square roots
- ▶ Coming up with a  $Q$  so that its execution mimics the proof tree can be difficult

# Examples

Sat Solving

Nonlinear Arithmetic

Any other problems with recursive proofs